Warning & Disclaimer

Do not modify or adjust the Z15-5D III (HD).
The Z15-5D III (HD) gimbal has been calibrated specifically for the designated camera and lens before it leaves the factory. Please mount only the designated camera and lens to the Z15-5D III (HD). No adjustments or modifications are needed. Do not add any other component/device (such as filters, lens hood, etc.) to the camera. Please use the original camera battery, otherwise performance may be hindered and internal malfunctions or damage may occur.

Only use the Z15-5D III (HD) gimbal with Flight Control Systems developed by DJI (such as the A2 or WooKong-M, and please upgrade to the latest firmware) for the greatest stability and precision. Please download the corresponding Assistant software and upgrade your Flight Control System’s Main Controller firmware, otherwise the Z15-5D III (HD) may not function properly. When the main battery power is connected, please be careful and operate the Flight Control System in the safest way possible. It is strongly recommended that you remove all propellers, use the R/C or flight pack battery power system, and keep children away during gimbal calibration and parameter setup. Carefully follow the appropriate steps to mount and connect the gimbal to your aircraft. Use this manual as well as the related Assistant software. Please respect the AMA’s National Model Aircraft Safety Code.

As DJI has no control over the use, setup, final assembly, modification (including use of non-specified DJI parts i.e. motors, ESCs, propellers, etc.) or misuse, no liability shall be assumed nor accepted for any resulting damage or injury. By the act of use, setup or assembly, the user accepts all resulting liability. DJI assumes no liability for damage(s) or injuries incurred directly or indirectly from the use of this product.

DJI and Zenmuse are registered trademarks of DJI. Names of products, brands, etc., appearing in this manual are trademarks or registered trademarks of their respective owner companies. This product and manual are copyrighted by DJI with all rights reserved. No part of this product or manual shall be reproduced in any form without the prior written consent or authorization of DJI.

Manual Tips

Legend

⚠️ Important
💡 Tips

Designated Camera and Lens Type for the Z15-5D III (HD) Gimbal

Camera Type: Canon 5D Mark III
Lens Type: Canon EF 24mm f/2.8 IS USM

Firmware versions of supporting DJI Flight Control Systems

WooKong-M: V5.26
A2: V2.1 or above
Product Profile

The Z15-5D III (HD) is a sophisticated gimbal specifically designed for aerial creativity. It has a built-in independent IMU module, special servo drive module, HDMI-HD/AV module, and more. The Z15-5D III (HD) performs well in all modes, including Orientation-locked, Non orientation-locked, and FPV (Reset).

### Working Modes

<table>
<thead>
<tr>
<th></th>
<th>Orientation-locked</th>
<th>Non orientation-locked</th>
<th>FPV (Reset)</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Gimbal Direction</strong></td>
<td>Gimbal pans with aircraft nose.</td>
<td>Gimbal pan and aircraft nose move separately.</td>
<td>Gimbal pan and aircraft nose are synchronized.</td>
</tr>
<tr>
<td><strong>Gimbal and Aircraft Nose Relative Angle</strong></td>
<td>The gimbal direction maintains the same relative angle to the aircraft nose.</td>
<td>The relative angle between the gimbal direction and aircraft nose is controllable.</td>
<td>The relative angle between the gimbal direction and aircraft nose is 0°.</td>
</tr>
<tr>
<td><strong>TX Control</strong></td>
<td>Controllable</td>
<td>Controllable</td>
<td>Uncontrollable</td>
</tr>
<tr>
<td><strong>Attitude Stability</strong></td>
<td>YES</td>
<td>YES</td>
<td>YES</td>
</tr>
<tr>
<td><strong>Vibration Reduction</strong></td>
<td>YES</td>
<td>YES</td>
<td>YES</td>
</tr>
<tr>
<td><strong>Stick Movement Definition</strong></td>
<td>The command stick controls gimbal rotation velocity. The stick center position is 0°/s, and its endpoint is maximum velocity.</td>
<td>Stick commands for gimbal rotation velocity are relative to total stick movement. The stick’s center position velocity is 0°/s. Its endpoint is the maximum velocity.</td>
<td>——</td>
</tr>
<tr>
<td><strong>Command Linearity</strong></td>
<td>YES</td>
<td>YES</td>
<td>——</td>
</tr>
</tbody>
</table>

Note*: Attitude stability means that the gimbal’s ROLL/TILT will not follow the aircraft’s ROLL/PITCH movement.
In the Box

Gimbal ×1

The Z15-5D III (HD) gimbal includes built-in servo drive modules, an independent IMU module and a HDMI-HD/AV module.

Gimbal Control Unit (GCU) ×1

Connect the GCU to your flight control system using the CAN-Bus cable. The GCU will control the gimbal’s pan, roll and tilt movements. Connect the GCU to video downlink for video signal.

Lens Retaining Ring ×1

For mounting the camera lens.

Mounting Bracket ×4

For mounting the gimbal to the landing gear.

Mounting Board for Receiver ×1

For attaching the GCU and providing a convenient mount for the receiver or other devices.

Cable Clamp ×1

For cable management.

Camera Mount Screw ×2

A standard tripod mounting screw.

Lens Retaining Ring Screw ×1

For attaching the lens retaining ring to the gimbal.
### In the Box

<table>
<thead>
<tr>
<th>Item</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Screw Package x1</strong></td>
<td>For mounting the gimbal to your aircraft (M2.5*8 cap head screw).</td>
</tr>
<tr>
<td><strong>10-Pin to 9-Pin Cable x 2</strong></td>
<td>For connecting the GCU to the gimbal.</td>
</tr>
<tr>
<td><strong>7-Pin Cable x 1</strong></td>
<td>For connecting the GCU to the Lightbridge air system.</td>
</tr>
<tr>
<td><strong>8-Pin to 6-Pin Cable x 2</strong></td>
<td>For connecting the GCU to the gimbal.</td>
</tr>
<tr>
<td><strong>Servo Cable Package x 1</strong></td>
<td>For connecting the GCU and the receiver.</td>
</tr>
<tr>
<td><strong>AV Video Power Cable x 1</strong></td>
<td>For connecting the GCU and the wireless video transmission module, and transmitting the AV signal.</td>
</tr>
<tr>
<td><strong>iOSD Mark II Cable x 1</strong></td>
<td>For connecting the GCU and the DJI iOSD MarkII.</td>
</tr>
<tr>
<td><strong>Micro-USB Cable x 1</strong></td>
<td>For adjusting parameters and upgrading the firmware via a PC.</td>
</tr>
<tr>
<td><strong>CAN-Bus Cable x 1</strong></td>
<td>For the CAN-Bus Flight Control System.</td>
</tr>
<tr>
<td><strong>Spare Package x 1</strong></td>
<td>Vibration Absorbers, Spare Screws, and Mounting Bracket.</td>
</tr>
</tbody>
</table>
**Gimbal Description**

⚠️ • To avoid motor damage, ensure there is nothing blocking the rotation of the servo drive modules.
• Clear obstacles or immediately cut off the power if any blockage occurs.

💡 • The servo drive modules have two motor command input ports and one private encoder port.
• The HDMI-HD/AV module converts HDMI to HD (or AV) using a cable connected to the camera HDMI port.
Camera Setup

Follow the steps below to configure your camera to work with the Z15-5D III (HD). Please read the relevant section for your camera.

**Canon 5D Mark III**

1. Set the shooting mode to Shutter-priority AE (Tv) or Manual exposure (M) by turning the Mode Dial.
2. Turn the Live View shooting/Movie shooting switch ( / ) to the Movie shooting position.
3. Press the AF.DRIVE button and select the drive mode as (10-sec. self-timer/Remote control) or (2-sec. self-timer/Remote control).
4. Turn the Image Stabilizer switch, located on the lens, to OFF.
5. It is recommended that you set the shutter speed from 1/100sec to 1/30sec. If the shooting mode is set to Manual exposure, please adjust the aperture properly and set the ISO speed to A (Auto).

💡 - The settings underlined above are strongly recommended. Failure to follow these settings may result in poor image quality.
   - The use of an SD card is preferred, as a CF card may affect the performance of the gimbal and lead to poor image quality.

Mount

Mounting the Lens

1. Mount the lens onto the camera as shown above.
Mounting the Camera

2. Mount the camera onto gimbal as shown above.
3. Adjust the camera and tighten the top camera mounting screw. Then tighten the bottom camera mounting screw and the lens retaining ring screw.

Mounting the Gimbal to the Landing Gear

The following diagram shows the gimbal mounted on a DJI S1000. You may also mount the gimbal onto different landing gear by referring to this diagram.
4. Mount the gimbal onto the landing gear with the mounting brackets. Tighten the screws and use threadlocker.

⚠️  • Ensure the lens is pointing in the same direction as the aircraft nose.
  • Ensure the top and bottom plates of the damping unit stay parallel when mounting. This prevents stretching and distortion.
  • Maintain good overall balance when mounting in order to ensure the center of gravity is balanced on each of the three axis lines.
  • The gimbal's center of gravity has been set by the factory. The center of gravity directly determines the gimbal’s overall performance. Do not adjust the gimbal’s center of gravity yourself.
  • The gimbal is highly precise and depends on this precision for optimal performance. Do not remove any screws on the gimbal, as this may result in poor performance or damage to the gimbal.
  • Do not unplug any cables attached to the gimbal ports or change the mechanical structure.
  • Make sure the wiring is correct, otherwise the gimbal may behave abnormally.

Camera Wiring and Shutter Control

Camera Wiring

The Z15-5D III (HD) gimbal can use a transmitter signal for shutter control. Ensure the camera is setup first, and then complete the following steps to connect the camera and the gimbal.

1. Connect the gimbal HDMI-HD/AV module to the camera HDMI port with a HDMI-HD/AV connection cable.
2. Toggle the HD/AV Switch to the AV position if using a normal wireless video TX module. Toggle the HD/AV Switch to the HD position if using a DJI HD wireless video TX module. (See Page 7 for the location of the HD/AV Switch)

⚠️  • When disconnecting the cable between the HDMI-HD/AV module and the camera, first dismount the camera, then unplug the HDMI-HD/AV interface.
  • Make sure to press the AF.DRIVE button and set the drive mode to (10-sec. self-timer/Remote control) or (2-sec. self-timer/Remote control).
Shutter Control

The Z15-5D III (HD) gimbal can transform a transmitter command into a shutter control signal. Select a 2-position switch/channel to use for remote shutter control.

For whichever 2-position switch you select, connect the correct receiver channel to the SHUT port. Toggling the 2-position works as follows:

Position-1 → Position-2: First shot
Position-2 → Position-1: Second shot

💡 If the shutter control does not work correctly, please check each step.

The following diagram shows how the shutter control works.

360° Panoramic Photograph Function

The Z15-5D III (HD) has a new 360° panoramic photograph function, which is controlled by the AUX1 channel. Toggle the AUX1 switch once to activate the function, and toggle it again to turn the function off.

Once the function is activated, the gimbal will adjust to a tilt angle of 0°. The pan axis will rotate, and every 30° the camera will take a photo. It will complete a 360° rotation, taking 12 photos along the way.

After that, the gimbal will adjust to a tilt angle of 30°. The pan axis will rotate, and every 30° the camera will take a photo. It will complete a 360° rotation, taking 12 photos along the way.

Next, the gimbal will adjust to a tilt angle of 60°. The pan axis will rotate, and every 30° the camera will take a photo. It will complete a 360° rotation, taking 12 photos along the way.

Last, the gimbal will adjust to a tilt angle of 90° and take 1 photo.

The camera will capture a total of 37 photos, with the entire process taking about 100 seconds.

During the procedure, you cannot use the remote control to move the gimbal. If you want to stop the procedure, toggle the AUX1 switch once and the gimbal will return to its normal operating mode.

⚠️ The gimbal will stay in place for 1.5 seconds for every photo capture. Set up the proper exposure time and focus mode so that both can be completed within 1.5 seconds.
Auto-calibration Function

The auto-calibration function is new to the Z15-5D III (HD) gimbal. It can help solve vibration problems that may be caused by the gimbal sensor drifting.

You can use the auto calibrate function when the following conditions are met:
1. The aircraft is on flat, level ground.
2. The landing gear is parallel to the aircraft IMU.
3. The initialization of the gimbal and aircraft is complete, and the gimbal is properly connected to the flight control system.

To auto-calibrate the gimbal:
1. Move the MODE channel control stick up and down quickly. After about 3 seconds, the gimbal will buzz twice and then begin auto-calibrating.
2. This process will last about 90 seconds. Do not touch the gimbal or aircraft during this time.
3. When the gimbal buzzes four times, the auto-calibration is complete. You can continue to operate the gimbal normally at this time.

Video Signal Transmission

A wireless video transmission module is required for remote video.

A. AV Wireless Video Transmission

1. Solder the AV Video Signal and GND cables to the wireless video transmission module air unit as shown above.
2. Plug the AV video power cable into the GCU’s G7 port.
3. Toggle the HD/AV Switch to the AV position. (See Page 7 for the location of the HD/AV Switch)
4. Power on the gimbal. If the gimbal LED indicator blinks yellow, it is functioning normally. If the LED indicator shows a continuous, unblinking yellow light, the video signal is lost. Check the connections between the camera and the HDMI video input.

- Complete the connection between the wireless video transmission module and the GCU before powering on the gimbal.
- A standard AV video power cable is recommended.
- Be sure to solder the AV video power cable to the wireless video transmission module correctly. As the cable carries power, ensure the cables are insulated or wrapped to prevent a short circuit.
- Connect the wireless video transmission module to a power source, as the GCU cannot supply power.

Make sure the power source provides a safe voltage for your own devices, according to the wireless video transmission module’s requirements.
B. DJI iOSD Mark II and AV Wireless Video Transmission

1. Connect the iOSD Mark II cable to the GCU’s G7 port.
2. Complete the other connections between the iOSD Mark II cable and the wireless video transmission module, according to their manuals.
3. Toggle HD/AV Switch to the AV position. (See Page 7 for the location of the HD/AV Switch)
4. Power on the gimbal. If the gimbal LED indicator blinks yellow, it is functioning normally. If the LED indicator shows a continuous, unblinking yellow light, the video signal is lost. Check the connections between the camera and the HDMI video input.

⚠️ Make sure to connect the wireless video transmission module and the iOSD MarkII cable to the GCU before powering on.

C. DJI Lightbridge Air System
This example is based on a Z15-5D III (HD) gimbal and the A2 flight control system.

1. Connect the Gimbal Port on the Lightbridge Air System to the G7 port on the Z15-5D III (HD) GCU using the supplied HD video power cable (7-pin cable).

2. Connect the DBUS port on the Lightbridge Air System to the DBUS port (X2 port) on the A2 flight control system. Toggle the HD/AV switch to the HD position.

3. Refer to the Lightbridge and A2 flight control system manuals to complete the connection.

⚠️ The HD video power cable is included with the Z15-5D III (HD) gimbal. To transmit gimbal and aircraft signals, connect the RC receiver to the DJI Lightbridge ground system when connecting the GCU.

- Always connect the wireless video transmission module to the GCU before powering on.
- A standard HD video power cable (7-pin cable) is recommended.
- Complete the other connections according to the Lightbridge user manual.
- If the gimbal LED indicator blinks red continuously, please power cycle the gimbal. (Power it off, then power it back on)

💡 If the video signal does not transmit, check each step.

The following diagram shows how a video signal is transmitted from the gimbal.

---

D. DJI Lightbridge 2

Connect the system as follows:

1. Connect the G7 port on the DJI HD gimbal and the CAN BUS port on the flight controller to the gimbal port on the Air System.

2. Connect the X2 DBUS port on the flight controller to the DBUS port on the Air System.

3. Refer to the user manuals for the gimbal and flight controller for details.
• Only use the DJI HD gimbal and DJI flight controller with the latest firmware. The GCU firmware for the HD gimbal must be v2.6 or above.
• If you are using the DJI A2 Flight Controller, connect the gimbal cable to the CAN 2 port on the flight controller.


In Dual Ground System Mode, the pan, tilt or roll motion of the camera can be controlled by the Slave Ground System, depending on your settings in the DJI GO app. Refer to the Lightbridge 2 User Manual for details.

**GCU Wiring**

**GCU Wiring**

The gimbal should be used with A2/WKM flight control system. The GCU wiring is based on WKM. For WKM, connect to any spare CAN-Bus port of the flight control system via a CAN-Bus cable.
**WKM**

Please refer to your WKM User Manual for all connection and configuration details.

**Gimbal Control Unit (GCU)**

1. Make sure all ports are accessible when installing your MC so as to facilitate wiring and software configuration.
2. In 3-pin ports, the pins near the nicks are the signal pins.
3. Use the 8-pin to 6-pin cable for the G6 port, and the 10-pin to 9-pin cable for the G9 port.
4. DO NOT cover the heat sinks, and keep them unobstructed at all times.
5. The IMU module is NOT waterproof or oil proof.

**RC Receiver**

1. The diagram on the previous page shows example connections. The aircraft signal will transmit through the DJI Lightbridge ground system. After connecting to the Lightbridge, it is not necessary to connect with the RC receiver.
2. Prepare 2 receivers, one for gimbal control, and the other for aircraft control. Refer to the 2-Pilots Solution for more detail.
3. If only one receiver is used for both aircraft and gimbal control, refer to the 1-Pilot Solution for more detail.
4. Setup the Aileron, Elevator, and Rudder channels on the gimbal control TX. The command stick will control gimbal rotation velocity. The center position is 0, and the end point is maximum velocity in both clockwise and counter clockwise directions. (The end point is 100%)
5. Choose one 3-position switch/channel to use as the Z15-5D III (HD) Working Mode switch. (MODE)
6. Choose one 2-position switch/channel to use as the camera shutter control switch (SHUT), and another 2-position switch to use as the camera lens orientation switch in Reset Mode (AUX2).
7. Please refer to the WKM User Manual for aircraft control settings. Connect the receiver to the GCU correctly.

💡 When using with A2 latest firmware version 2.5, all of the gimbal channels can be setup through the A2 receiver. Refer to A2 User Manual for details.
## GCU Ports

The following table shows the connections between the GCU channels and the relevant TX channels.

<table>
<thead>
<tr>
<th>TX Channels</th>
<th>GCU Channels</th>
<th>Indications</th>
</tr>
</thead>
<tbody>
<tr>
<td>JR</td>
<td>Futaba/Hitec</td>
<td><strong>ROLL</strong></td>
</tr>
<tr>
<td><strong>ELEV</strong></td>
<td>2</td>
<td><strong>TILT</strong></td>
</tr>
<tr>
<td><strong>RUDD</strong></td>
<td>4</td>
<td><strong>PAN</strong></td>
</tr>
<tr>
<td><strong>AUX2</strong></td>
<td>7</td>
<td><strong>MODE</strong></td>
</tr>
</tbody>
</table>

2-position switch channel

<table>
<thead>
<tr>
<th>Channels</th>
<th>Indications</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SHUT</strong></td>
<td>For camera shutter control (both taking photos and recording video are available). Off if disconnected.</td>
</tr>
</tbody>
</table>

2-position switch channel

<table>
<thead>
<tr>
<th>Channels</th>
<th>Indications</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>AUX1</strong></td>
<td>For the 360° Panoramic Photograph Function.</td>
</tr>
</tbody>
</table>

2-position switch channel

<table>
<thead>
<tr>
<th>Channels</th>
<th>Indications</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>AUX2</strong></td>
<td>When AUX2 is connected to a 2-position switch channel, it is used as a camera orientation (down or forward) switch in FPV Mode (Reset). The camera orientation is forward if disconnected. Or if you are using a S-Bus receiver, connect the receiver to the AUX2 port.</td>
</tr>
</tbody>
</table>

2-position switch channel or PPM channel

<table>
<thead>
<tr>
<th>Channels</th>
<th>Indications</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>AUX3</strong></td>
<td>When the AUX3 is connected to a 2-position switch channel, it is used to toggle video recording. If you are using a PPM receiver, connect the receiver to the AUX3 port.</td>
</tr>
</tbody>
</table>

The following table shows the corresponding relationship between the GCU and the S-Bus/PPM channels.

<table>
<thead>
<tr>
<th>S-Bus/PPM Channels</th>
<th>GCU Channels</th>
<th>S-Bus/PPM Channels</th>
<th>GCU Channels</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td><strong>ROLL</strong></td>
<td>5</td>
<td><strong>SHUT</strong></td>
</tr>
<tr>
<td>2</td>
<td><strong>TILT</strong></td>
<td>8</td>
<td><strong>AUX1</strong></td>
</tr>
<tr>
<td>4</td>
<td><strong>PAN</strong></td>
<td>9</td>
<td><strong>AUX2</strong></td>
</tr>
<tr>
<td>7</td>
<td><strong>MODE</strong></td>
<td>6</td>
<td><strong>AUX3</strong></td>
</tr>
</tbody>
</table>

## Working Mode /AUX1/AUX2/AUX3 Switch Setup

### Working Mode Switch Settings

Whenever 3-position switch you select to use as the Working Mode switch, wire the relevant channel from the receiver to the MODE port. At each switch position, use end-point fine tuning to set channel AUX2(JR) or 7(Futaba/Hitec) for all three Working Modes:
Orientation-locked               Back to center
FPV (Reset)                     MODE channel end-point 60%~90%
Non orientationlocked           MODE channel end-point 60%~90%

⚠️ • The gimbal will work in Orientation-locked mode if the MODE channel is disconnected.
    • FPV mode is the default startup mode when the MODE channel is connected.
    • The Working Mode from the previous power cycle will be retained if the cable between MODE and the RC receiver is disconnected during operation.

💡 • For a 3-position switch, you may assign:
    Position-1 to Non orientation-locked
    Position-2 to FPV Mode (Reset)
    Position-3 to Orientation-locked
    Position-1 and Position-3 can be inversely assigned.
    • One 2-position switch can be assigned for any two of the working modes, if preferred.

AUX1 Switch Settings

The Z15-5D III (HD) gimbal has a 360° panoramic photograph function. Choose a 2-position switch as AUX1 switch for this function and wire the relevant channel of the receiver to the AUX1 port. Toggle the switch once to turn on the function and toggle again to turn off the function.

AUX2 Switch Settings

The Z15-5D III (HD) supports toggling the camera lens down or forward in FPV Mode (Reset). Please choose a 2-position switch for this function and wire the relevant channel of the receiver to the AUX2 port. You may assign: Position-1 to DOWN; Position-2 to FORWARD; or reverse the assignment.

⚠️ • This function will only work in FPV Mode (Reset).
    • When this function is active, if the Working Mode is ever changed to FPV Mode (Reset), the gimbal will force the camera lens to face forward or down, depending on current the location of the AUX2 switch.
    • The camera orientation is forward if AUX2 is disconnected.

💡 If AUX2 is connected to a Futaba S-Bus channel, it is then used as the input channel for S-Bus control.
AUX3 Switch Settings

The Z15-5D III (HD) supports starting and stopping your camera’s video record function by using a 2-position switch through AUX3. Connect the relevant channel of the receiver to the AUX3 port. Toggle the switch to start/stop recording.
Position-1: Start recording
Position-2: Stop recording

PC Assistant Tuning

Installation and Usage

1. Ensure the most recent drivers are installed correctly. This should have been done before using the A2 or WooKong-M software.
2. Download the appropriate Assistant installer from DJI.com.
3. Double click the Assistant installer and follow the steps to finish the installation.
4. Run Assistant.
5. Upgrade the firmware or configure parameters using Assistant as needed.

⚠️ The Assistant installer can be used on Windows XP, Win7, and Win8 (32 or 64 bit).

Basic Setting

You can set transmitter channels for roll, tilt and pan control, and also switch between working modes during flight. Move your cursor to each area or refer to this manual for more details.
Upgrade

You can view the latest firmware version information on this page. Upgrade the firmware by following the steps below:
1. Connect the gimbal to your computer with a Micro-USB cable, and wait until the blue indicator LED in the Assistant software is blinking.
2. Click “Upgrade”.
3. Wait for the download to finish.
4. Click “Upgrade” again and then click “Confirm”.
5. Power cycle the gimbal (turn it off, then on again) after the upgrade is complete.

⚠️ • Ensure your computer is connected to the internet.
   • Close any antivirus programs and network firewalls during the upgrade.
   • Ensure the gimbal is powered on during the upgrade.
   • Do not disconnect the USB cable during the upgrade.

Info

You can check the Assistant version via Info.
S/N is a 32 digit authorization code for function activations. The authorization code for your unit is filled in at the time of manufacture. In the future, you may be asked to fill in a new S/N if you require function upgrades. Fill in the S/N and then click the Write button. If you fill in an invalid S/N more than 30 times, your gimbal will be locked and you will have to contact our customer support.
Pre-Flight Check

- Ensure the gimbal is properly installed and attached to the landing gear, and that the camera is mounted correctly and securely.
- Before powering on, spin the gimbal through its complete rotation by hand on each axis to ensure nothing is blocking its movement.
- Ensure all cables are connected correctly, without any plugged in backwards or into the wrong ports.
- Ensure the AV video power cable is properly soldered and shielded if an AV video transmission module is used.
- Verify TX settings.
- Ensure the camera menu options and settings are correct.
- Verify a proper connection between the GCU and the RC receiver.
- Verify a proper connection between the GCU and the flight control system.
- Ensure the latest Flight Control System Main Controller firmware is installed.

💡 Refer to the Gimbal LED Indicator section in the Appendix to understand the connection status between the camera and gimbal.
- Refer to the Troubleshooting section in the Appendix if an abnormal situation occurs.
Flight Test

1. Ensure the batteries are fully charged for your TX, GCU, and all of the other devices on your aircraft.
2. Make sure all connections and wiring are in good condition.
3. Switch on the TX.
4. Adjust the camera to a level position on the roll axis of the gimbal.
5. Power on the gimbal and wait for the self initialization test to complete. The roll, yaw and pitch axis will rotate quickly at the same time.
6. After self-initialization, the camera lens will point towards the aircraft’s nose and each axis of the gimbal should be in the position illustrated above.
7. The gimbal will then go into a second stage of initialization. At this time, each axis will rotate very slowly.
8. Once each axis stops moving, the gimbal is fully initialized and ready to use.
9. Toggle the assigned Working Modes switch on your TX and make sure it is working properly.
10. Switch the Working Modes to Non orientation-locked, FPV Mode (Reset), and Orientation-locked Mode respectively. Then push the controller sticks lightly in the Roll, Tilt and Pan directions to check that the gimbal moves in the corresponding directions. If not, see Working Mode/AUX2 Switch Setup to correct your settings.

⚠️ If the gimbal does not match the diagram after initialization, please refer to the Troubleshooting section in Appendix.
Appendix

Attention

For safety reasons, please pay careful attention to all of the following items:

1. To avoid motor damage, ensure nothing blocks the servo drive module’s total range of movement.
2. Before powering on, spin the gimbal through its complete rotation by hand on each axis to ensure nothing is blocking the mechanical movement of the gimbal.
3. Be sure to mount the side of servo drive module 1 with the ports facing towards the aircraft tail.
4. The gimbal’s center of gravity has been preset. The gimbal balance is directly related to its performance. Please do not adjust the gimbal’s center of gravity by yourself.
5. The gimbal is a sophisticated device. Do not remove any screws from the gimbal. Doing so may result in poor performance or even damage.
6. Do not unplug any cables attached to the gimbal ports or change the mechanical structure.
7. Make sure all wiring is correct, otherwise the gimbal may not operate correctly or efficiently.
8. Make sure to connect the wireless video transmission module to the GCU prior to powering on the system.
9. We recommend use of the included AV video power cable, if needed.
10. Be sure to solder the AV video power cable to the wireless video transmission module correctly. Ensure the cables are insulated and protected to prevent any type of short circuit.
11. Pay close attention to the voltage of S1000 and be sure it is within the defined limits (6S) when using one battery for both the S1000 and as a power supply for the gimbal.
12. Never touch the contact points of a power cable to the gimbal; this may lead to a short circuit of the gimbal, resulting in complete failure.
13. Before powering on, adjust the roll axis of the gimbal to be level.

1-Pilot Solution

![Diagram of 1-Pilot Solution]
1. Prepare one 14-channel TX/RC receiver for the aircraft and gimbal control. Above is an example of the wiring configuration.
2. Setup the Aileron, Elevator, Throttle, and Rudder channels on your TX for aircraft roll, elevator, throttle, and rudder control. Also, connect the TX’s AUX2 for aircraft control modes (Please refer to your Flight Control System’s user manual).
3. Choose three 3-position switches to use for the gimbal ROLL, TILT, and PAN rotation control. The center position of each switch is 0 velocity, and the end point positions are maximum velocity.
4. Choose one 3-position switch/channel as the gimbal’s Working Modes switch (MODE).
5. Choose one 2-position switch/channel as the camera shutter control switch (SHUT).
6. Connect the receiver to the GCU and Flight Control System Main Controller correctly.

## 2-Pilot Solution

- Two transmitters and two receivers are required.
- Transmitter A and receiver A are used to control the gimbal.
- Transmitter B and receiver B are used to control the aircraft.

Make the connections as shown in the diagram below:

Please refer to the GCU Wiring section for more details.
## Port Descriptions

### GCU

<table>
<thead>
<tr>
<th>Port</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ROLL</td>
<td>For roll axis control</td>
</tr>
<tr>
<td>TILT</td>
<td>For tilt axis control</td>
</tr>
<tr>
<td>PAN</td>
<td>For pan axis control</td>
</tr>
<tr>
<td>MODE</td>
<td>For Working Mode switch</td>
</tr>
<tr>
<td>SHUT</td>
<td>For camera shutter control and auto-calibration function</td>
</tr>
<tr>
<td>AUX1</td>
<td>For the 360° panoramic photograph function</td>
</tr>
<tr>
<td>AUX2</td>
<td>For Gimbal Orientation (down or forward) switch in FPV Mode ; S-Bus Receiver</td>
</tr>
<tr>
<td>AUX3</td>
<td>For the video recording control ; PPM Receiver</td>
</tr>
</tbody>
</table>

### G7

1. Connect to the wireless video transmission module, for transmitting AV or HD signals
2. Connect to DJI Lightbridge, for transmitting HD, gimbal and aircraft control signals

### G6

Connect to Gimbal, for transmitting motor commands

### G9

Connect to Gimbal, for transmitting the video signal

### Micro-USB port:

Micro-USB port: for PC connection (Assistant configuration and firmware upgrades)

### XT60

Connect to the battery (or to GIMBAL if DJI S1000 is used)

### CAN-Bus port:

CAN-Bus port: Use CAN-Bus Cable to connect GCU to the flight control system

### Gimbal

<table>
<thead>
<tr>
<th>Port</th>
<th>Connection</th>
</tr>
</thead>
<tbody>
<tr>
<td>HDMI-HD/AV Port</td>
<td>To Camera HDMI port</td>
</tr>
<tr>
<td>Motor Command Input Port</td>
<td>To GCU G6</td>
</tr>
<tr>
<td>10-Pin to 9-Pin Cable Port</td>
<td>To GCU G9</td>
</tr>
</tbody>
</table>

### Gimbal LED Indicator

<table>
<thead>
<tr>
<th>Description</th>
<th>LED Indicator</th>
</tr>
</thead>
<tbody>
<tr>
<td>HD mode, HDMI-HD/AV module transmits normally</td>
<td>⬜️ ⬜️ ⬜️ ⬜️ ⬜️ ⬜️ ⬜️ ⬜️ LED is blinking green.</td>
</tr>
<tr>
<td>HD mode, without camera HDMI video input</td>
<td>⬜️ ⬜️ Green LED is solid on.</td>
</tr>
<tr>
<td>HD mode, DJI Lightbridge App video source has been set to “HDMI/AV”</td>
<td>⬜️ ⬜️ Yellow LED is solid on.</td>
</tr>
<tr>
<td>AV mode, HDMI-HD/AV module transmits normally</td>
<td>⬜️ ⬜️ ⬜️ ⬜️ ⬜️ ⬜️ ⬜️ ⬜️ LED is blinking yellow.</td>
</tr>
<tr>
<td>AV mode, without camera HDMI video input</td>
<td>⬜️ ⬜️ Yellow LED is solid on.</td>
</tr>
<tr>
<td>HD video transmission module and gimbal is disconnected</td>
<td>⬜️ ⬜️ ⬜️ ⬜️ ⬜️ ⬜️ ⬜️ ⬜️ LED is blinking red.</td>
</tr>
</tbody>
</table>
## Troubleshooting

<table>
<thead>
<tr>
<th>NO.</th>
<th>The Problem</th>
<th>The Cause</th>
<th>What to Do</th>
</tr>
</thead>
</table>
| 1   | The gimbal keeps drifting after initialization. | (1) The TX trims are too high.  
(2) The GCU and Flight Control System have been disconnected.  
(3) The gimbal direction is not pointing in the same direction as the aircraft’s nose. | (1) Adjust the TX trims.  
(2) Connect the GCU and Flight Control System.  
(3) Ensure the gimbal direction is pointing in the same direction as the aircraft’s nose. |
| 2   | The gimbal is in an incorrect position after initializing. | Abnormal calibration after manufacturing. | Please contact your local dealer or DJI customer service. |
| 3   | Cannot distinguish the gimbal’s direction when in use. | BVR (Beyond Visibility Range) flight. | Switch to FPV Mode first, then to another Working Mode as needed. |
| 4   | The gimbal LED is blinking red. | (1) There is a disconnected cable between the gimbal and camera.  
(2) The camera is off.  
(3) Camera setup failure. | (1) Make sure all cables are securely connected.  
(2) Power on the camera.  
(3) Set the HDMI resolution to 1080i. |
| 5   | The gimbal’s green or yellow LED is continuously on, but no video is displayed. | (1) The HDMI-HD/AV transmission module is disconnected from the camera.  
(2) The camera is powered off.  
(3) In HD mode, the DJI Lightbridge App video source has been set to “HDMI/AV”. | (1) Check HDMI-HD/AV transmission module connection.  
(2) Power on the camera.  
(3) Change the DJI Lightbridge App video source to “HD Gimbal”. |
## Specifications

### General

<table>
<thead>
<tr>
<th>Built-In Functions</th>
<th>Orientation-locked control</th>
<th>Non orientation-locked control</th>
<th>FPV mode (Reset)</th>
<th>HDMI-HD/AV module</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>• Three Working Modes</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• Built-in independent IMU</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>module</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• DJI gimbal special servos</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>drive module</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• Wireless video transmission supported</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• Camera shutter control supported</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• Wide range voltage input supported</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• S-Bus/PPM Receiver supported</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• 360° panoramic photograph function</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• Auto-calibration function</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Peripheral

<table>
<thead>
<tr>
<th>Supported Camera</th>
<th>CANON EOS 5D MARK III</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supported Lens</td>
<td>CANON EF 24mm f/2.8 IS USM</td>
</tr>
<tr>
<td>GCU Input Power</td>
<td>4S–12S LiPo (Recommend 6S if with S1000)</td>
</tr>
<tr>
<td>Control Requirement</td>
<td>At least four spare receiver channels</td>
</tr>
<tr>
<td>Assistant Software System Requirements</td>
<td>Windows XP SP3; Windows 7; Windows 8 (32 or 64 bit)</td>
</tr>
</tbody>
</table>

### Mechanical & Electrical Characteristics

<table>
<thead>
<tr>
<th>Working Current</th>
<th>• Static current: 200mA (@25V)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>• Dynamic current: 400mA (@25V)</td>
</tr>
<tr>
<td></td>
<td>• Locked-rotor current: 4A (@25V)</td>
</tr>
<tr>
<td>Operating Temperature</td>
<td>-10°C ~ 50°C</td>
</tr>
<tr>
<td>Weight</td>
<td>1.53Kg</td>
</tr>
<tr>
<td>Dimensions</td>
<td>281mm × 242mm × 222mm</td>
</tr>
<tr>
<td>GCU Weight</td>
<td>63g</td>
</tr>
<tr>
<td>GCU Dimensions</td>
<td>64.2 mm × 34.1mm × 19.5mm</td>
</tr>
</tbody>
</table>

### Working Performance

| Load Weight (Reference Value) | 2664g(5D MARK III with SD Card & Battery & CANON EF 24mm f/2.8 IS USM Lens) |
| Controlled Angle Accuracy    | ±0.02°                         |
| Maximum Controlled Rotation Speed* | Pan axis: ±90°/s |
|                               | Tilt axis: ±130°/s             |
|                               | Roll axis: ±30°/s              |
| Controlled Rotation Range    | Pan axis control: ±360° continuous rotation |
|                               | Tilt axis control: +15°/-90°   |
|                               | Roll axis control: ±25°        |

Note*: Gimbal’s Maximum Controlled Rotation Speed corresponds to TX stick input pushed to 100% end-points.