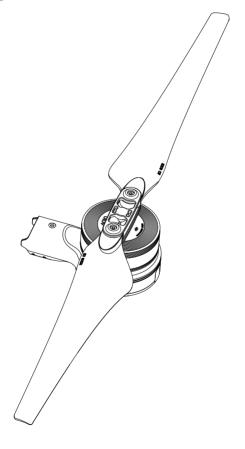
# E2000 PRO

# **Tuned Propulsion System**

多旋翼动力系统

User Manual 用户手册

V1.4 2016.12





#### Disclaimer

Thank you for purchasing the E2000 Pro Tuned Propulsion System (hereinafter referred to as "product"). Read this disclaimer carefully before using this product. By using this product, you hereby agree to this disclaimer and signify that you have read it fully. Please install and use this product in strict accordance with the User Manual, SZ DJI TECHNOLOGY CO., LTD. and its affiliated companies assume no liability for damage(s) or injuries incurred directly or indirectly from using, installing or refitting this product improperly, including but not limited to using non-designated accessories.

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This disclaimer is produced in various languages. In the event of variance among different versions, the Chinese version shall prevail when the product in question is purchased in Mainland China, and the English version shall prevail when the product in question is purchased in any other region.

## Warning

When powered on, the motors and propellers will rotate very quickly and can cause serious damage or injuries. Always be vigilant and make safety your top priority.

- 1. The allowable voltage of the E2000 Pro can reach 52.2 V. Be sure to use it in strict accordance with the related safety rules.
- 2. Always attempt to fly your aircraft in areas free of people, animals, power lines, and other obstacles.
- 3. DO NOT approach or touch the motors or propellers when the unit is powered on.
- 4. Ensure that there are no open circuits or short circuits when soldering the power cables.
- 5. Before takeoff, ensure that the propellers and motors are installed correctly and the propellers are unfolded.
- 6. Ensure that all parts of the aircraft are in good condition. DO NOT fly with worn or damaged parts.
- 7. Ensure that all parts are firmly in place and all screws are tight before each flight.
- 8. Only use compatible, authorized DJI parts.

#### Legend

Important



: Hints and Tips

#### Instruction

The E2000 Pro Tuned Propulsion System is a multirotor propulsion system designed for multirotor aircraft with a payload of 1.8 - 2.5 kg/ rotor. It is ideal for industrial applications and professional photography in rugged environments.

The new design of the powertrain provides effective protection for internal

components while making assembly and configuration more convenient. A brand new motor uses a centrifugal fan to improve heat dissipation. Its airtight structure keeps out liquid and foreign objects, protecting the inner parts of the motor against dust and liquid corrosion.

Reinforced blades and the perfect aerodynamic design give the Z-Blade 21-inch foldable propellers ultra-high strength and rigidity.

The Smart ESC uses a sinusoidal drive powered by advanced algorithms to allow for a responsive motor drive with precise control. Like most DJI products, the ESC firmware can be updated to ensure optimal performance for the E2000 Pro.

## 1. Parts

ΕN

The Powertrain (CW or CCW, screws included) and Updater can be purchased separately on the DJI Online Store.



Powertrain (Clockwise)



Powertrain (Counterclockwise)



Screw Pack: Arm Screws (M3x:10 Hex) Anti-rotation Screws (M3x:6.5 Hex) ESC Board Screws (M2x4) Motor Screws (M3x:8 Thumb) ESC Cover Screws (M2.5x6) Propeller Blade Screws (M4x13.3 Hex) Propeller Cover Screws (M3x9 Hex) Propeller Washers, Propeller Lockrings

# 2. Gain Value Settings

The E2000 Pro ESC features a sinusoidal drive, replacing the traditional square-wave drive, to offer improved performance during rotor acceleration and deceleration.

To achieve the same sensitivity as square-wave-driven ESCs, the gain values must be reduced according to your flight control system and airframe. The table below shows typical gain values when using the E2000 Pro with a DJI A2 flight control system, a six-rotor frame with a diagonal distance of 1100 mm, and at a takeoff weight of 14 kg:

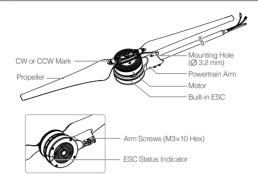
Basic Gain			Attitude Gain		
Pitch	Roll	Yaw	Pitch	Roll	Vertical
130%	130%	100%	150%	150%	100%

# 3. Mounting the Powertrains

 Use a suitable airframe that can withstand the large thrust delivered by the E2000 Propulsion System.



- ↑ The powertrains are compatible with frame arms with an outer diameter of 28 mm. Mount the powertrains to appropriate frame arms only.
  - · Identify the clockwise and counter-clockwise marks on the propellers and mount the powertrains onto the corresponding frame arms.



#### Tools Required: M3 hex key

- 1) Loosen the two arm screws (M3×10 hex) on the powertrain arm.
- 2) Pull the cables of the powertrain through the frame arm. Then insert the frame arm into the powertrain arm.
- 3) Align the components so that the propeller is oriented upright after assembly.
- 4) OPTIONAL: Use an anti-rotation screw (included) and M3×6.5 hex screw holding base customized to the tube used (not included) or rivet (not included) to secure the position of the powertrain arm to achieve optimal performance.
- 5) Tighten the two screws (M3×10 hex) on the powertrain arm.

## 4. Connecting the Cables

Tools Required: Electric soldering iron and soldering tin



- 1) Solder the power cables of each powertrain to the frame's power system. Make sure that the solder points are strong and that there is no chance for a short circuit. The red cable should be attached to the positive terminal and the black cable should be attached to the negative terminal.
- 2) Connect the signal cable to your flight controller. The signal cable's orange wire transmits the control signal; the brown wire is for ground.



Make sure there are no short circuits or open circuits.

## 5. Using the DJI ESC Assistant

The DJI ESC Assistant is used to update the ESC firmware and configure the propulsion system. Be sure to remove the propellers before using the ESC Assistant.



Before using the Updater, unplug any other serial devices that are connected to your computer, then follow the instructions below:

- 1) Download and install the DJI ESC Assistant from the official DJI website (http://www.dji.com/product/e2000/info#downloads).
- 2) Connect the Updater to the ESC with a JST 3-pin cable; connect it to your computer with a Micro USB cable.
- 3) Connect a 12S LiPo battery to the ESC to supply power to the system. Do not disconnect the ESC from the computer or power supply until the configuration is complete.
- 4) Launch the DJI ESC Assistant, Observe the indicators at the bottom of the window. When a connection is established, the Connection Status Indicator (left) will glow solid green and the Data Exchange Indicator (right) will blink blue.
- 5) Click the 'View' tab. In the 'ESC' section, check the current firmware version and ensure the installed firmware is up-to-date. If not, click the hyperlink and follow the instructions to update it.
- 6) In the 'LED Color' section, you can customize the colors of the ESC Status Indicators.



If the ESC is not recognized by the DJI ESC Assistant (the Data Exchange Indicator remains inactive blue), check if there is more than one FTDI device connected such as another DJI Updater. an FTDI USB adapter or development board (e.g. a BeagleBone, Raspberry or Arduino board). Unplug the other FTDI devices, restart the DJI ESC Assistant and ESC, and try again.

## 6. ESC Blinking Patterns and Beeping Sounds

You can instantly tell the ESC's status by observing the LED indicator and emitted sounds.

LED Indicator	Sound	Description
Blinking Yellow and Green alternately	None	Motor is connecting.
Breathing Red or breathing Green	<b>♪</b> 1356	System ready.
B—/ G— Solid Red or solid Green	None	Motor started normally.
Binking Red and Yellow alternately	None Double Beep Triple Beep	Self-test failed. Abnormal input voltage. Motor parameters and ESC firmware data do not match.

Blinking Yellow rapidly	Single Beep	Starting input signal is not at minimum. Check the settings of your flight controller, receiver and remote controller.
Blinking Yellow slowly	Slow Beep	No signal input.
Solid Yellow	None	Motors are rotating at full throttle.
Blinking Red rapidly	None	Motor stalled and ESC locked. Land your aircraft immediately, stop the motors, and power it off. Then check if the motors are damaged.
®: ×2 ····· Blinks Red twice	None	ESC high temperature (above 100°C). Land your aircraft immediately and power it off. Wait for the ESC to cool down to room temperature.

#### 7. Specifications Max Thrust 5100 g/rotor (50 V, Sea Level) Recommended Battery 12S LiPo Recommended Takeoff Weight 1800 - 2500 g/rotor (Sea Level) Powertrain Weight (Single) 430 g Powertrain Cable Length 750 mm Compatible Frame Arm Outer Diameter 28 mm Operating Temperature -10° to 50° C **ESC** Max Allowable Voltage 52.2 V Max Allowable Current (Continuous) 25 A Max Peak Current (< 3 sec) 40 A PWM Input Signal Level 3.3 V / 5 V Compatible Operating Pulse Width 1120 - 1920 µs Signal Frequency 30 Hz to 450 Hz 12S LiPo Battery Motor Stator Size 60 × 10 mm ΚV 130 rpm/V Weight 230 g Propeller Diameter × Thread Pitch 21 × 7 inch (533 × 178 mm) Weight (Single Propeller) 58 g

#### Motor Dimensions







## 8. Performance and Parameters

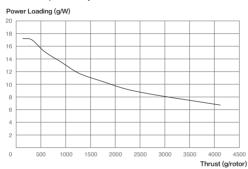
Use the data below to facilitate the proper use of the propulsion system.



ΕN

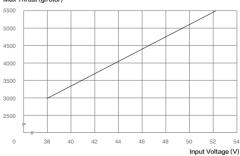
- · A payload less than half of the maximum thrust is recommended for optimal performance.
- · DO NOT overload the system. A payload more then 2/3 of the maximum thrust will severely compromise safety and performance.

### E2000 Propulsion System Performance

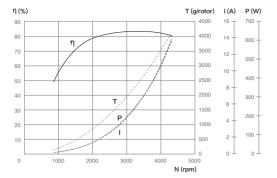


The data above was measured with an input voltage of 44.4 V, at room temperature and sea level. The thrust was adjusted by the throttle.

#### Max Thrust (g/rotor)



The data above was measured at full throttle, at room temperature and sea level.

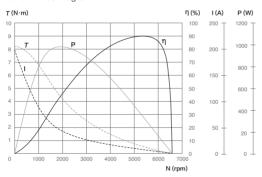


η - Electrical Efficiency, T - Thrust, I - Current, P - Input Power, N - Rotational Speed

The data above was measured with an input voltage of 44.4 V, at room temperature and sea level. The rotational speed was adjusted by the throttle.

#### 6010 Motor Performance

#### Performance Diagram



T - Torque, η - Efficiency, I - Current, P - Output Power, N - Rotational Speed

The data above contain theoretical values measured with an input voltage of 44.4 V, for reference only. When operating at a temperature of 25°C with no additional cooling devices, the motor cannot operate with a current more than 20 A. It can support short term operation (about 10 to 30 sec) with a current between 15 A and 20 A, and continuous operation with a current under 15 A. The motor run time should depend on the actual environmental temperature and cooling conditions.

#### Characteristic Parameters

Speed Constant	130 rpm/V
Back-Electromotive Force Constant	0.0734 V·s/rad
Mechanical Time Constant	200 ms
Motor Rotor Inertia	70 kg·mm²
Total Rotor Inertia (Propeller Included)	700 kg·mm²

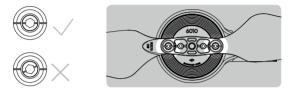
Torque Constant	0.076 N·m/A
Line-to-Line Inductance	0.224 mH
Line-to-Line Resistance	230 mΩ
Thermal Constant	600 s

#### 9. FAQ

ΕN

#### How do I check if the propellers are secure and will not fly off?

Make sure you check the marks on the screws and cover on the propeller before each flight. If the propeller is loose, the marks will not line up, indicating that the screws should be tightened.

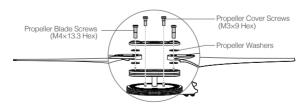


 $\triangle$ 

If the two propeller blade screws are swapped or other screws are used, the marks may not be accurate.

# How do I replace the propeller blades or propeller covers if they are damaged?

- Prepare two propeller blade screws (M4x13.3 hex), two propeller cover screws (M3x9 hex), and four propeller washers.
- Apply threadlocker to the two screw holes on the motor and the propeller cover.
- 3) Assemble the propeller and tighten with two propeller blade screws (M4x13.3 hex) so that the blades can fold smoothly. Mount the propeller onto the motor and use two propeller cover screws (M3x9 hex) to secure the propeller.



 $\triangle$ 

Ensure the screw is secured tightly for the threadlocker to be effective.

## **Compliance Information**

#### FCC Compliance

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) This device must accept any interference received, including interference that may cause undesired operation.

Any changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

#### **EU Compliance Statement**

SZ DJI TECHNOLOGY CO., LTD. hereby declares that this device is in compliance with the essential requirements and other relevant provisions of the EMC Directive.

A copy of the EU Declaration of Conformity is available online at www.dji.com/euro-compliance



EU contact address: DJI GmbH, Industrie Strasse. 12, 97618, Niederlauer, Germany

Manufactured by:

14th floor, West Wing, Skyworth Semiconductor Design Building NO.18 Gaoxin South 4th Ave, Nanshan District, Shenzhen, Guangdong, China

DJI Support www.dji.com/support

The content is subject to change.

Download the latest version from http://www.dji.com/product/e2000



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## 产品使用注意事项

СН

高速旋转的螺旋桨可能会对人身财产造成一定程度的伤害和破坏,因此在使用 E2000 专业版时,请务必注意安全。

- 1. E2000 专业版最大允许电压高达 52.2 V,务必遵守相关安全规范 讲行操作。
- 2. 使用时请远离不安全因素,如障碍物、人群、高压线等。
- 3. 切勿贴近或接触旋转中的电机或螺旋桨,避免被旋转中的螺旋桨 割伤。
- 4. 确保电源线焊接正确, 电路无短路、无开路。
- 5. 使用前请检查螺旋桨和电机是否安装正确,折叠桨是否已展开。
- 6. 使用前请检查各零部件是否完好。如有部件老化或损坏,请更换新 部件。
- 7. 每次飞行前, 检查飞行器各部分结构及螺丝是否松动。
- 8. 请使用 DJI 提供的零配件。

## 符号说明

▲ 重要注意事项



# 简介

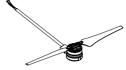
E2000 专业版是一款单轴负载 1.8 - 2.5 kg 的多旋翼动力系统,适合行业应用及专业航拍。一体式动力总成,全面保护内部元件,安装调试简单快捷。全新电机配备离心风扇,提供强效冷却; 封闭式结构设计,有效阻止异物进入及液体腐蚀。Z-Blade 21 寸折叠桨采用最新一代翼型和优秀的气动设计,提供充足的结构强度和刚度。正弦驱动的智能电调搭载先进专利算法,实现精准敏捷的电机驱动控制; 固件支持用户自行升级,方便用户享受未来的新功能。

## 1. 相关物品

E2000 专业版的动力总成(CW或CCW,附带螺丝包)、升级器均 为单个独立包装,用户需分别购买。



动力总成 (CW)



动力总成 (CCW)



螺丝句,

力臂固定螺丝(M3×10,内六角) 力臂防旋螺丝(M3×6.5,内六角) 电调固定螺丝 (M2×4) 电调保护盖螺丝 (M2.5×6) 电机固定螺丝(M3×8,大头)

桨叶螺丝(M4×13.3,内六角) 桨盖螺丝(M3×9),螺旋桨垫片,螺旋桨防松圈

# 2. 感度参数调节

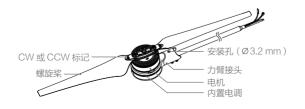
E2000 专业版配备全新电调,使用正弦驱动代替传统的方波驱动、提 升了加减速性能。使用前,用户需要根据所使用的机架及飞控系统适 当降低感度参数。下表是配合 DJI A2 飞控系统和轴距为 1100 mm 的 六轴机架使用,起飞重量为 14 kg 时的一组典型参数:

基本感度			姿态感度		
俯仰	横滚	航向	俯仰	横滚	垂直
130%	130%	100%	150%	150%	100%

# 3. 安装动力总成



- · E2000 动力系统的拉力较大, 务必确保您所选用机架的结 构强度与动力系统提供的拉力匹配。
- · 动力总成适用于外径 28 mm 的碳管, 请安装至符合规格的 碳管上。
- ·安装时,请注意区分螺旋桨上的 CW 或 CCW 标记,将其安 装到对应的机臂碳管上。



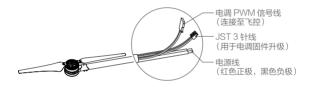


工具(自备):适用于力臂固定螺丝(M3×10,内六角)的扳手

- 1) 拧松动力总成上的两颗 M3×10 力臂固定螺丝。
- 2) 将动力总成的四根线穿过碳管, 然后将碳管插入力臂接头中。
- 3) 旋转碳管,保证其安装至机架后动力总成的螺旋桨朝向正上方。
- 4)根据需要,在安装孔处使用力臂防旋螺丝(M3×6.5内六角,需按 照所用碳管自行定制内衬)或合适的铆钉锁住碳管,以防动力总成 转动影响飞行。(选装)
- 5) 拧紧动力总成上的两颗 M3×10 力臂固定螺丝。

## 4. 系统连线

### 工具和材料(自备): 电烙铁和焊锡



- 将电源线焊到您机架的电源系统上,注意焊点牢固并且不会出现短路。电源线红色为正极,黑色为负极。
- 将电调 PWM(脉宽调制)信号线连接至飞控。其中橙色线为控制信号线,棕色线为地线。

△ 请确保电路中没有短路或开路。

# 5. 使用电调助手

电调助手主要用于电调固件升级、系统配置等。连接电调助手前,务 必确保螺旋桨已拆下。



使用升级器前,请移除计算机上的其他串口设备,然后按照以下步骤 操作:

1) 从 DJI 官方网站下载并运行电调助手安装程序,按照提示完成软件 安装。(http://www.dji.com/cn/product/e2000/info#downloads)

СН

- 2) 将动力总成的 JST 3 针线接入升级器,使用 Micro USB 线连接升 级器与计算机。
- 3) 连接 12S LiPo 电池为内置电调供电,设置完成前请勿切断电源或 断开连接。
- 4) 运行电调助手并等待动力总成的内置电调与软件连接。PC 连接指 示灯(左)绿灯常亮,通信指示灯(右)蓝灯闪烁,表示电调与软 件连接上并能正常诵信。
- 5) 单击"香看"选项卡, 在"ESC"界面中香看固件版本, 如果服务器 上的固件较新干您的当前版本,点击相应的链接按照提示进行升级。
- 6) 在 "LED 颜色"界面设置电调状态指示灯颜色。

Λ 若电调助手无法识别电调(软件界面左下角绿灯常亮,蓝灯 熄灭), 请检查计算机是否接有多个 D.JI 升级器、FTDI USB 适配器或其他可能使用到 FTDI 芯片组的开发工具(包括但不 限于: BeagleBone、Raspberry、Arduino等)。如果是, 请断开其他 FTDI 设备,仅保留一个 DJI 升级器,然后重启电 调助手,重新为电调供电,即可恢复正常。

## 6. 电调状态指示灯及提示音描述

使用时, 请根据电调状态指示灯及鸣音判断产品是否正常工作。如果 出现异常, 请排查故障。

指示灯状态	提示音	描述	
演	无	识别电机	
② 一 / ⑧ 一 红灯或绿灯呼吸点亮	<b>♪</b> 1356	就绪	
<ul><li>① — / ⑧ —</li><li>红灯或绿灯常亮</li></ul>	无	电机正常启动	
	无	上电自检未通过	
- 道: 黄:	BBBB···	上电时输入电压异常	
红黄灯交替闪烁	BBBBBB···	识别的电机参数与固件存储不 匹配	
赏 黄灯快闪	BBBB	上电时输入油门量不在最小值,请检查主控、接收机或遥控器设置	
黄	BBB···	无信号输入	
◉ ── 黄灯常亮	无	满油门旋转	
黨 红灯快闪	无	电机堵转,电调已锁死 请立即降落飞行器关闭电机并 断开电源,然后检查电机是否 受损	
	无	电调温度过高(超过 100℃) 请立即降落飞行器关闭电机并 断开电源,等待电调冷却	

## 7. 产品规格

最大拉力 5100克/轴(50V,海平面)

推荐电池 12S LiPo

推荐起飞重量 1800 - 2500 克 / 轴 (海平面)

动力总成线组长度 750 mm

适用碳管外径 28 mm

动力总成重量(单个) 430 g

使用环境温度 -10 至 50℃

电调

CH

最大允许电压 52.2 V 最大允许电流(持续) 25 A 最大允许峰值电流(3 秒 ) 40 A

PWM 输入信号电平 3.3 V / 5 V 兼容

工作脉宽 1120 - 1920 µs

兼容信号频率 30 - 450 Hz

电池 12S LiPo

电机

定子尺寸 60×10 mm KV 值 130 rpm/V

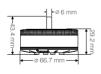
重量 230 g

螺旋桨

直径 × 螺距 533×178 mm (21×7 inch)

重量(单个螺旋桨) 58 g

## 电机尺寸







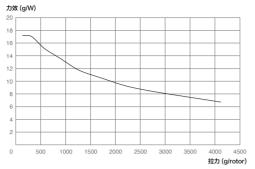
## 8. 性能参数

请根据以下性能参数合理使用动力系统。

↑ ・建议载重小于最大拉力的一半,以获得最佳性能。

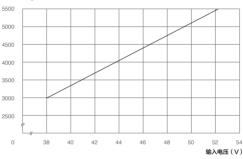
请勿超重飞行,载重超过最大拉力的 2/3 会严重影响性能以及安全性。

## F2000 动力系统性能

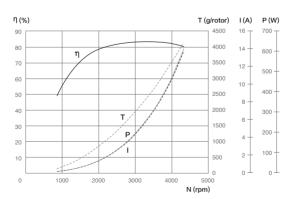


以上数据为电调输入电压 44.4 V、室温 25°C、海平面高度的环境下,变化油门输入调 节拉力测得。





以上数据为室温 25℃、海平面高度的环境下,电调满油门,调节电调输入电压测得。

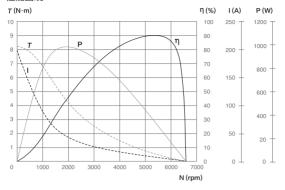


η- 电效率, T- 拉力, I- 电流, P- 输入功率, N- 转速

以上数据均为电调输入电压 44.4 V、室温 25℃、海平面高度的环境下,变化油门输入 调节转速测得。

### 6010 电机性能

#### 性能曲线



## T- 扭矩, η- 效率, I- 电流, P- 输出功率, N- 转速

以上数据均为输入电压 44.4 V 时的理论值,仅供参考。在室温 25℃、无额外冷却装置 的情况下, 电流超过 20 A 为不可工作区域, 15-20 A 为短时(约 10-30 s)工作区域, 15 A 以下为可持续工作区域。实际使用时,请根据工作环境温度和散热条件控制电机运 行时间。

#### 特征参数

CH

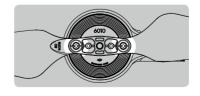
速度常数	130 rpm/V	扭矩常数	0.0760 N·m/A
反电动势常数	0.0734 V·s/rad	线电感	0.224 mH
机械时间常数	200 ms	线电阻	$230~m\Omega$
电机转子惯量	70 kg·mm²	热时间常数	600 s
转子总惯量(含桨)	700 kg·mm²		

## 9. 常见问题

#### 如何预防射桨?

螺丝和桨盖上印有标识线来提示螺丝是否松动。每次起飞前都检查此 标识线,确保飞行安全。





若在安装时交换两颗桨叶螺丝的安装位置或使用其它的螺丝, 此标识线将失去参照作用。

Λ

#### 如何更换桨叶或桨盖?

- 1) 使用2颗桨叶螺丝(M4×13.3,内六角)、2颗桨盖螺丝(M3×9, 内六角)和4个螺旋桨垫片重新安装螺旋桨。
- 2) 在桨盖和电机上的安装孔螺纹内使用螺丝胶。
- 3) 安装桨叶螺丝(M4×13.3,内六角)至桨叶被夹紧且可自由旋转, 然后安装两颗桨盖螺丝(M3×9,内六角)并拧紧。



确保拧紧螺丝。螺丝过松可能会导致螺丝胶无法完全干燥 固化。

制 造 商: 深圳市大疆创新科技有限公司

地 址:深圳市南山区高新南四道 18 号创维半导体设计大厦西座 14 层

服务热线: 400-700-0303

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